$$\begin{split} &\dot{x_1} = x_2 \\ &\dot{x_2} = -\dot{x_1} - \dot{x_1^3} - \dot{x_2} \\ &\text{Choose as a candidate for V}(\mathbf{x}) = \frac{1}{2} x_2^2, \text{ with } \\ &\dot{V} = x_2 \dot{x_2} = -x_1 x_2 - x_1^3 x_2 - x_2^2 \end{split}$$

The first and second term of the right-hand side are indefinite. But we can integrate them directly, because they are the derivatives of $-\frac{1}{2}x_1^2$ and $-\frac{1}{4}x_1^4$

This leads to
$$\frac{d}{dt} \{ \frac{1}{2} \mathbf{X}_1^2 + \frac{1}{4} \mathbf{X}_1^4 + \frac{1}{2} \mathbf{X}_2^2 \} = -\mathbf{X}_2^2 \}$$

So the Lyapunov function $V(x) = \frac{1}{2} x_1^2 + \frac{1}{4} x_1^4 + \frac{1}{2} x_2^2$

is positive definite and $\frac{dV}{dt} = -x_2^2$ is positive negative and thus the system is globally asymptotic stable.